Understanding Quantum Information and Computation

Lesson 8

Grover's Algorithm

John Watrous

Unstructured search

Let $\Sigma = \{0, 1\}$ denote the binary alphabet (throughout the lesson).

Suppose we're given a function

$$f: \Sigma^n \to \Sigma$$

that we can compute efficiently.

Our goal is to find a solution, which is a binary string $x \in \Sigma^n$ for which f(x) = 1.

Search

Input: $f: \Sigma^n \to \Sigma$

Output: a string $x \in \Sigma^n$ satisfying f(x) = 1, or "no solution" if no such

strings exist

This is <u>unstructured</u> search because f is arbitrary — there's <u>no promise</u> and we can't rely on it having a structure that makes finding solutions easy.

Algorithms for search

Search

Input: $f: \Sigma^n \to \Sigma$

Output: a string $x \in \Sigma^n$ satisfying f(x) = 1, or "no solution" if no such

strings exist

Hereafter let us write

$$N = 2^n$$

By iterating through all $x \in \Sigma^n$ and evaluating f on each one, we can solve Search with N queries.

This is the best we can do with a *deterministic* algorithm.

<u>Probabilistic</u> algorithms offer minor improvements, but still require a number of queries linear in N.

Grover's algorithm is a quantum algorithm for Search requiring $O(\sqrt{N})$ queries.

Phase query gates

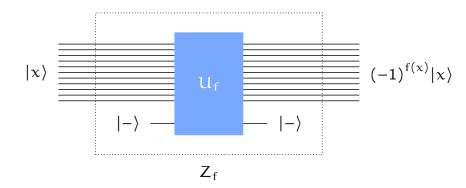
We assume that we have access to the function $f: \Sigma^n \to \Sigma$ through a query gate:

$$U_f: |\alpha\rangle|x\rangle \mapsto |\alpha \oplus f(x)\rangle|x\rangle$$
 (for all $\alpha \in \Sigma$ and $x \in \Sigma^n$)

(We can build a circuit for U_f given a Boolean circuit for f.)

The *phase query gate* for f operates like this:

$$Z_f: |x\rangle \mapsto (-1)^{f(x)} |x\rangle$$
 (for all $x \in \Sigma^n$)



Exercise: show how to build a U_f operation using a controlled Z_f operation.

Phase query gates

The *phase query gate* for f operates like this:

$$Z_f: |x\rangle \mapsto (-1)^{f(x)} |x\rangle$$
 (for all $x \in \Sigma^n$)

We're also going to need a phase query gate for the n-bit OR function:

$$OR(x) = \begin{cases} 0 & x = 0^{n} \\ 1 & x \neq 0^{n} \end{cases}$$
 (for all $x \in \Sigma^{n}$)

$$Z_{OR}|x\rangle = \begin{cases} |x\rangle & x = 0^n \\ -|x\rangle & x \neq 0^n \end{cases}$$
 (for all $x \in \Sigma^n$)

Algorithm description

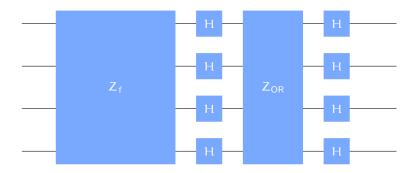
Grover's algorithm

- 1. *Initialize:* set n qubits to the state $H^{\otimes n}|0^n\rangle$.
- 2. *Iterate*: apply the *Grover operation* t times (for t to be specified later).
- 3. Measure: a standard basis measurement yields a candidate solution.

The Grover operation is defined like this:

$$G = H^{\otimes n} Z_{OR} H^{\otimes n} Z_f$$

 Z_f is the phase query gate for f and Z_{OR} is the phase query gate for the n-bit OR function.



Algorithm description

Grover's algorithm

- 1. *Initialize*: set n qubits to the state $H^{\otimes n}|0^n\rangle$.
- 2. *Iterate*: apply the *Grover operation* t times (for t to be specified later).
- 3. Measure: a standard basis measurement yields a candidate solution.

The Grover operation is defined like this:

$$G = H^{\otimes n} Z_{OR} H^{\otimes n} Z_{f}$$

 Z_f is the phase query gate for f and Z_{OR} is the phase query gate for the n-bit OR function.

A typical way that Grover's algorithm can be applied:

- 1. Choose the number of iterations t (next section).
- 2. Run Grover's algorithm with t iterations to get a candidate solution x.
- 3. Check the solution. If f(x) = 1 then output x, otherwise either run Grover's algorithm again (possibly with a different t) or report "no solutions."

Solutions and non-solutions

We'll refer to the n qubits being used for Grover's algorithm as a register Q.

We're interested in what happens when Q is initialized to the state $H^{\otimes n}|0^n\rangle$ and the Grover operation G is performed iteratively.

$$G = H^{\otimes n} Z_{OR} H^{\otimes n} Z_f$$

These are the sets of non-solutions and solutions:

$$A_0 = \left\{ x \in \Sigma^n : f(x) = 0 \right\}$$

$$A_1 = \{x \in \Sigma^n : f(x) = 1\}$$

We will be interested in *uniform superpositions* over these sets:

$$|A_0\rangle = \frac{1}{\sqrt{|A_0|}} \sum_{x \in A_0} |x\rangle$$

$$|A_1\rangle = \frac{1}{\sqrt{|A_1|}} \sum_{x \in A_1} |x\rangle$$

Analysis: basic idea

$$A_{0} = \{x \in \Sigma^{n} : f(x) = 0\} \qquad A_{1} = \{x \in \Sigma^{n} : f(x) = 1\}$$
$$|A_{0}\rangle = \frac{1}{\sqrt{|A_{0}|}} \sum_{x \in A_{0}} |x\rangle \qquad |A_{1}\rangle = \frac{1}{\sqrt{|A_{1}|}} \sum_{x \in A_{1}} |x\rangle$$

The register Q is first initialized to this state:

$$|u\rangle = H^{\otimes n}|0^n\rangle = \frac{1}{\sqrt{N}}\sum_{x\in\Sigma^n}|x\rangle$$

This state is contained in the subspace spanned by $|A_0\rangle$ and $|A_1\rangle$:

$$|u\rangle = \sqrt{\frac{|A_0|}{N}}|A_0\rangle + \sqrt{\frac{|A_1|}{N}}|A_1\rangle$$

The state of Q $\frac{1}{2}$ remains in this subspace after every application of the Grover operation G.

We can better understand the Grover operation by splitting it into two parts:

$$G = (H^{\otimes n} Z_{OR} H^{\otimes n})(Z_f)$$

1. Recall that Z_f is defined like this:

$$Z_f|x\rangle = (-1)^{f(x)}|x\rangle$$
 (for all $x \in \Sigma^n$)

Its action on $|A_0\rangle$ and $|A_1\rangle$ is simple:

$$Z_f|A_0\rangle = |A_0\rangle$$

$$Z_f|A_1\rangle = -|A_1\rangle$$

We can better understand the Grover operation by splitting it into two parts:

$$G = (H^{\otimes n} Z_{OR} H^{\otimes n})(Z_f)$$

2. The operation Z_{OR} is defined like this:

$$Z_{OR}|x\rangle = \begin{cases} |x\rangle & x = 0^n \\ -|x\rangle & x \neq 0^n \end{cases}$$
 (for all $x \in \Sigma^n$)

Here's an alternative way to express Z_{OR} :

$$Z_{OR} = 2|0^n\rangle\langle 0^n| - 1$$

Using this expression, we can write $H^{\otimes n}Z_{OR}H^{\otimes n}$ like this:

$$H^{\otimes n}Z_{OR}H^{\otimes n} = H^{\otimes n}(2|0^n)\langle 0^n|-1)H^{\otimes n} = 2|u\rangle\langle u|-1$$

$$Z_{f}|A_{0}\rangle = |A_{0}\rangle$$

$$Z_{f}|A_{1}\rangle = -|A_{1}\rangle$$

$$|u\rangle = \sqrt{\frac{|A_{0}|}{N}}|A_{0}\rangle + \sqrt{\frac{|A_{1}|}{N}}|A_{1}\rangle$$

$$G|A_{0}\rangle = (2|u\rangle\langle u| - 1)Z_{f}|A_{0}\rangle$$

$$= (2|u\rangle\langle u| - 1)|A_{0}\rangle$$

$$= 2\sqrt{\frac{|A_{0}|}{N}}|u\rangle - |A_{0}\rangle$$

$$= 2\sqrt{\frac{|A_{0}|}{N}}(\sqrt{\frac{|A_{0}|}{N}}|A_{0}\rangle + \sqrt{\frac{|A_{1}|}{N}}|A_{1}\rangle) - |A_{0}\rangle$$

$$= \frac{|A_{0}| - |A_{1}|}{N}|A_{0}\rangle + \frac{2\sqrt{|A_{0}| \cdot |A_{1}|}}{N}|A_{1}\rangle$$

$$Z_{f}|A_{0}\rangle = |A_{0}\rangle$$

$$Z_{f}|A_{1}\rangle = -|A_{1}\rangle$$

$$|u\rangle = \sqrt{\frac{|A_{0}|}{N}}|A_{0}\rangle + \sqrt{\frac{|A_{1}|}{N}}|A_{1}\rangle$$

$$G|A_0\rangle = \frac{|A_0| - |A_1|}{N} |A_0\rangle + \frac{2\sqrt{|A_0| \cdot |A_1|}}{N} |A_1\rangle$$

$$G|A_{1}\rangle = (2|u\rangle\langle u| - 1)Z_{f}|A_{1}\rangle$$

$$= (1 - 2|u\rangle\langle u|)|A_{1}\rangle$$

$$= |A_{1}\rangle - 2\sqrt{\frac{|A_{1}|}{N}}|u\rangle$$

$$= |A_{1}\rangle - 2\sqrt{\frac{|A_{0}|}{N}}(\sqrt{\frac{|A_{0}|}{N}}|A_{0}\rangle + \sqrt{\frac{|A_{1}|}{N}}|A_{1}\rangle)$$

$$= -\frac{2\sqrt{|A_{0}| \cdot |A_{1}|}}{N}|A_{0}\rangle + \frac{|A_{0}| - |A_{1}|}{N}|A_{1}\rangle$$

$$Z_{f}|A_{0}\rangle = |A_{0}\rangle$$

$$Z_{f}|A_{1}\rangle = -|A_{1}\rangle$$

$$|u\rangle = \sqrt{\frac{|A_{0}|}{N}}|A_{0}\rangle + \sqrt{\frac{|A_{1}|}{N}}|A_{1}\rangle$$

$$G|A_{0}\rangle = \frac{|A_{0}| - |A_{1}|}{N} |A_{0}\rangle + \frac{2\sqrt{|A_{0}| \cdot |A_{1}|}}{N} |A_{1}\rangle$$

$$G|A_{1}\rangle = -\frac{2\sqrt{|A_{0}| \cdot |A_{1}|}}{N} |A_{0}\rangle + \frac{|A_{0}| - |A_{1}|}{N} |A_{1}\rangle$$

The action of G on span $\{|A_0\rangle, |A_1\rangle\}$ can be described by a 2 × 2 matrix:

$$M = \begin{pmatrix} \frac{|A_0| - |A_1|}{N} & -\frac{2\sqrt{|A_0| \cdot |A_1|}}{N} \\ \frac{2\sqrt{|A_0| \cdot |A_1|}}{N} & \frac{|A_0| - |A_1|}{N} \end{pmatrix} \quad |A_0\rangle$$

$$|A_0\rangle \qquad |A_1\rangle$$

Rotation by an angle

The action of G on span{ $|A_0\rangle$, $|A_1\rangle$ } can be described by a 2 × 2 matrix:

$$M = \begin{pmatrix} \frac{|A_0| - |A_1|}{N} & -\frac{2\sqrt{|A_0| \cdot |A_1|}}{N} \\ \frac{2\sqrt{|A_0| \cdot |A_1|}}{N} & \frac{|A_0| - |A_1|}{N} \end{pmatrix} = \begin{pmatrix} \sqrt{\frac{|A_0|}{N}} & -\sqrt{\frac{|A_1|}{N}} \\ \sqrt{\frac{|A_1|}{N}} & \sqrt{\frac{|A_0|}{N}} \end{pmatrix}^2$$

This is a *rotation* matrix.

$$\begin{pmatrix} \sqrt{\frac{|A_0|}{N}} & -\sqrt{\frac{|A_1|}{N}} \\ \sqrt{\frac{|A_1|}{N}} & \sqrt{\frac{|A_0|}{N}} \end{pmatrix} = \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix} \qquad \theta = \sin^{-1}\left(\sqrt{\frac{|A_1|}{N}}\right)$$

$$M = \begin{pmatrix} \cos(2\theta) & -\sin(2\theta) \\ \sin(2\theta) & \cos(2\theta) \end{pmatrix}$$

Rotation by an angle

$$M = \begin{pmatrix} \cos(2\theta) & -\sin(2\theta) \\ \sin(2\theta) & \cos(2\theta) \end{pmatrix} \qquad \theta = \sin^{-1}\left(\sqrt{\frac{|A_1|}{N}}\right)$$

After the initialization step, this is the state of the register Q:

$$|u\rangle = \sqrt{\frac{|A_0|}{N}}|A_0\rangle + \sqrt{\frac{|A_1|}{N}}|A_1\rangle = \cos(\theta)|A_0\rangle + \sin(\theta)|A_1\rangle$$

Each time the Grover operation G is performed, the state of Q is rotated by an angle 2θ :

$$|u\rangle = \cos(\theta)|A_0\rangle + \sin(\theta)|A_1\rangle$$

$$G|u\rangle = \cos(3\theta)|A_0\rangle + \sin(3\theta)|A_1\rangle$$

$$G^2|u\rangle = \cos(5\theta)|A_0\rangle + \sin(5\theta)|A_1\rangle$$

$$\vdots$$

$$G^t|u\rangle = \cos((2t+1)\theta)|A_0\rangle + \sin((2t+1)\theta)|A_1\rangle$$

Geometric picture

Main idea

The operation $G = H^{\otimes n} Z_{OR} H^{\otimes n} Z_f$ is a composition of *two reflections:*

$$Z_f$$
 and $H^{\otimes n}Z_{OR}H^{\otimes n}$

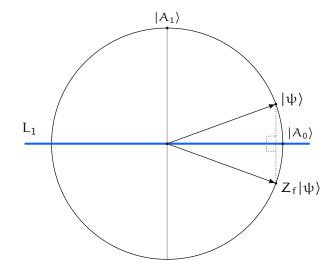
Composing two reflections yields a *rotation*.

1. Recall that Z_f has this action on the 2-dimensional space spanned by $|A_0\rangle$ and $|A_1\rangle$:

$$Z_f|A_0\rangle = |A_0\rangle$$

 $Z_f|A_1\rangle = -|A_1\rangle$

This is a reflection about the line L_1 parallel to $|A_0\rangle$.



Geometric picture

Main idea

The operation $G = H^{\otimes n} Z_{OR} H^{\otimes n} Z_f$ is a composition of *two reflections:*

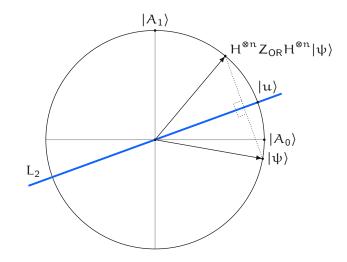
$$Z_f$$
 and $H^{\otimes n}Z_{OR}H^{\otimes n}$

Composing two reflections yields a *rotation*.

2. The operation $H^{\otimes n}Z_{OR}H^{\otimes n}$ can be expressed like this:

$$H^{\otimes n}Z_{OR}H^{\otimes n} = 2|u\rangle\langle u| - 1$$

Again this is a *reflection*, this time about the line L_2 parallel to $|u\rangle$.



Geometric picture

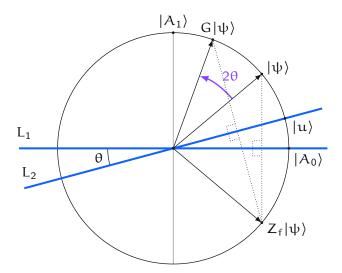
Main idea

The operation $G = H^{\otimes n} Z_{OR} H^{\otimes n} Z_f$ is a composition of *two reflections:*

$$Z_f$$
 and $H^{\otimes n}Z_{OR}H^{\otimes n}$

Composing two reflections yields a *rotation*.

When we compose two reflections, we obtain a *rotation* by twice the angle between the lines of reflection.



Setting the target

Consider any quantum state of this form:

$$\alpha |A_0\rangle + \beta |A_1\rangle$$

Measuring yields a solution $x \in A_1$ with probability $|\beta|^2$.

$$\alpha |A_0\rangle + \beta |A_1\rangle = \frac{\alpha}{\sqrt{|A_0|}} \sum_{x \in A_0} |x\rangle + \frac{\beta}{\sqrt{|A_1|}} \sum_{x \in A_1} |x\rangle$$

$$p(x) = \begin{cases} \frac{|\alpha|^2}{|A_0|} & x \in A_0 \\ \frac{|\beta|^2}{|A_1|} & x \in A_1 \end{cases}$$

Pr(outcome is in
$$A_1$$
) = $\sum_{x \in A_1} p(x) = |\beta|^2$

Setting the target

Consider any quantum state of this form:

$$\alpha |A_0\rangle + \beta |A_1\rangle$$

Measuring yields a solution $x \in A_1$ with probability $|\beta|^2$.

The state of Q after t iterations in Grover's algorithm:

$$\cos \bigl((2t+1)\theta \bigr) |A_0\rangle + \sin \bigl((2t+1)\theta \bigr) |A_1\rangle \qquad \theta = \sin^{-1} \left(\sqrt{\frac{|A_1|}{N}} \right)$$

Measuring after t iterations gives an outcome $x \in A_1$ with probability

$$\sin^2((2t+1)\theta)$$

We wish to maximize this probability — so we may view that $|A_1\rangle$ is our *target state*.

Setting the target

The state of Q after t iterations in Grover's algorithm:

$$\cos \bigl((2t+1)\theta \bigr) |A_0\rangle + \sin \bigl((2t+1)\theta \bigr) |A_1\rangle \qquad \theta = \sin^{-1} \Biggl(\sqrt{\frac{|A_1|}{N}} \Biggr)$$

Measuring after t iterations gives an outcome $x \in A_1$ with probability

$$\sin^2((2t+1)\theta)$$

To make this probability close to 1 and minimize t, we will aim for

$$(2t+1)\theta \approx \frac{\pi}{2} \qquad \Longleftrightarrow \qquad t \approx \frac{\pi}{4\theta} - \frac{1}{2} \stackrel{\text{closest integer}}{\longrightarrow} \quad t = \left\lfloor \frac{\pi}{4\theta} \right\rfloor$$

Important considerations:

- t must be an integer
- θ depends on the number of solutions $s = |A_1|$

Unique search

$$(2t+1)\theta \approx \frac{\pi}{2} \quad \Leftarrow \quad t = \left\lfloor \frac{\pi}{4\theta} \right\rfloor$$

Unique search

Input: $f: \Sigma^n \to \Sigma$

Promise: There is exactly one string $z \in \Sigma^n$ for which f(z) = 1,

with f(x) = 0 for all strings $x \neq z$

Output: The string z

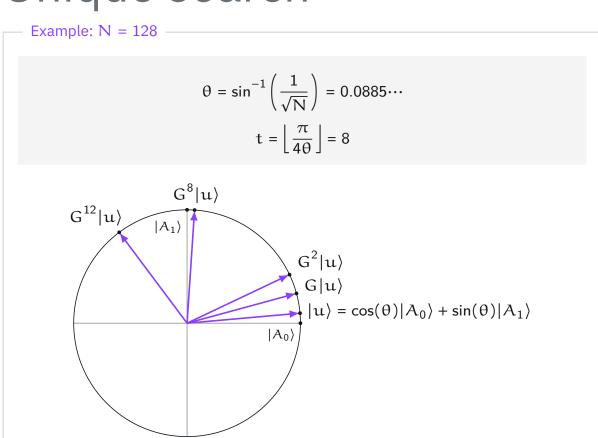
For Unique search we have $s = |A_1| = 1$ and therefore

$$\theta = \sin^{-1} \left(\sqrt{\frac{1}{N}} \right) \approx \sqrt{\frac{1}{N}}$$

Substituting $\theta \approx 1/\sqrt{N}$ into our expression for t gives

$$t \approx \left| \frac{\pi}{4} \sqrt{N} \right| \leftarrow O(\sqrt{N})$$
 queries

Unique search



Unique search

$$\theta = \sin^{-1}\left(\sqrt{\frac{1}{N}}\right) \qquad t = \left\lfloor \frac{\pi}{4\theta} \right\rfloor$$

Measuring after t iterations gives the (unique) outcome $x \in A_1$ with probability

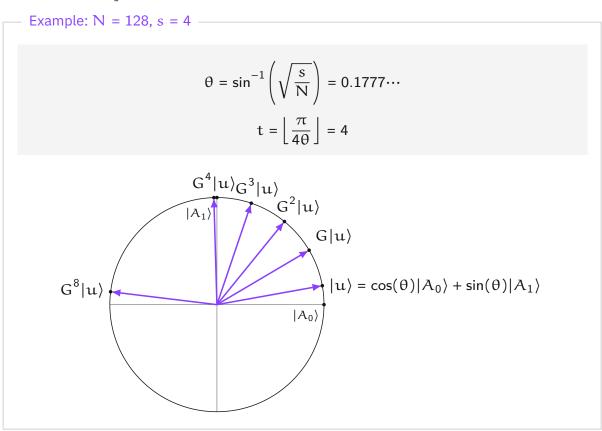
$$p(N,1) = \sin^2((2t+1)\theta)$$

Success	probabi	lities for	Unique	search

Ν	p(N,1)	N	p(N,1)
2	.5	128	.9956199
4	1.0	256	.9999470
8	.9453125	512	.9994480
16	.9613190	1024	.9994612
32	.9991823	2048	.9999968
64	.9965857	4096	.9999453

It can be proved analytically that $p(N, 1) \ge 1 - 1/N$.

Multiple solutions



Multiple solutions

$$\theta = \sin^{-1}\left(\sqrt{\frac{s}{N}}\right) \qquad t = \left\lfloor \frac{\pi}{4\theta} \right\rfloor$$

For every $s \in \{1, ..., N\}$, the probability p(N, s) to find a solution satisfies

$$p(N, s) \ge \max\left\{1 - \frac{s}{N}, \frac{s}{N}\right\}$$

Number of queries

$$\theta = \sin^{-1}\left(\sqrt{\frac{s}{N}}\right) \qquad t = \left\lfloor \frac{\pi}{4\theta} \right\rfloor$$

Each iteration of Grover's algorithm requires 1 query (or evaluations of f). How does the number of queries t depend on N and s?

$$\sin^{-1}(x) \ge x$$
 (for every $x \in [0, 1]$)
$$\theta = \sin^{-1}\left(\sqrt{\frac{s}{N}}\right) \ge \sqrt{\frac{s}{N}}$$

$$t \le \frac{\pi}{4\theta} \le \frac{\pi}{4}\sqrt{\frac{N}{s}}$$

$$t = O\left(\sqrt{\frac{N}{s}}\right)$$

Unknown number of solutions

What do we do if we don't know the number of solutions in advance?

A simple approach

Choose the number of iterations $t \in \{1, ..., |\pi\sqrt{N}/4|\}$ uniformly at random.

- The probability to find a solution (if one exists) will be at least 40%.
 (Repeat several times to boost success probability.)
- The number of queries (or evaluations of f) is $O(\sqrt{N})$.

A more sophisticated approach

- 1. Set T = 1.
- 2. Run Grover's algorithm with $t \in \{1, ..., T\}$ chosen uniformly at random.
- If a solution is found, output it and stop.
 Otherwise, increase T and return to step 2 (or report "no solution").
- The rate of increase of T must be carefully balanced: slower rates require more queries, higher rates decrease success probability. $T \leftarrow \left[\frac{5}{4}T\right]$ works.
- If the number of solutions is $s \ge 1$, then the number of queries (or evaluations of f) required is $O(\sqrt{N/s})$. If there are no solutions, $O(\sqrt{N})$ queries are required.

Concluding remarks

- Grover's algorithm is asymptotically optimal.
- Grover's algorithm is *broadly applicable*.
- The technique used in Grover's algorithm can be generalized.